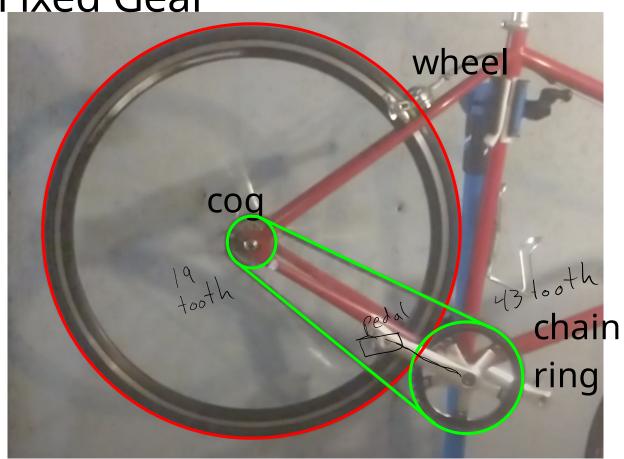
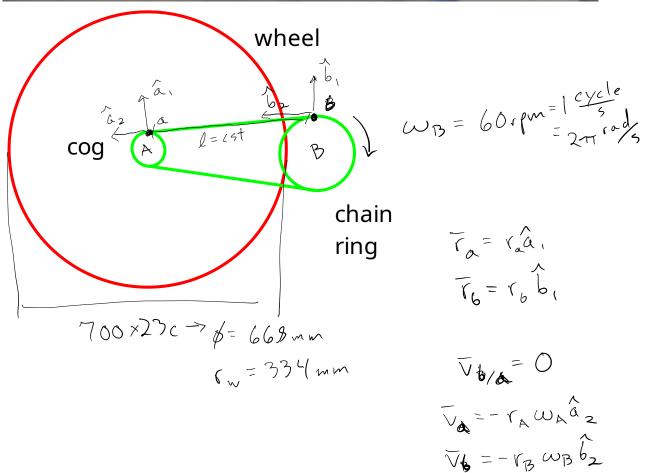
## **Bike Gear Kinematics:**

Fixed Gear





V<sub>B</sub> = V<sub>A</sub> + V<sub>B/A</sub>

V<sub>A</sub>W<sub>A</sub> = r<sub>B</sub> W<sub>B</sub> => 19 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub>

W<sub>A</sub> = 
$$\frac{43}{19}$$
 W<sub>B</sub>

W<sub>A</sub> = 2.26 (1 Hz) = 2.26 rot / 5

How fast am I riding??

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>B</sub> · r<sub>B</sub>W<sub>B</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>A</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>A</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub> · r<sub>A</sub>W<sub>A</sub> = 4/2 + ooth / 2πr<sub>A</sub>

W<sub>A</sub> = 1 + ooth / 2πr<sub>A</sub>

W<sub>A</sub> = 1